

Periodic solution for a delay integro-differential equation in biomathematics

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Abstract

Sufficient conditions for the existence and uniqueness of periodic solution of a delay integro-differential equation which arise in biomathematics are given. The results use a bidimensional variant of the Perov's fixed point theorem.

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1 Introduction

In this paper we consider a model for the spread of certain infectious disease with a contact rate that varies seasonally. This model is governed by the following integro-differential equation

$$x(t) = \int_{t-\tau}^t f(s, x(s), x'(s)) ds \quad (1)$$

where:

- (i) $x(t)$ is the proportion of infectious in population at time t ;
- (ii) $\tau > 0$ is the length of time in which an individual remains infectious;
- (iii) $x'(t)$ is the speed of infectivity;

(iv) $f(t, x(t), x'(t))$ is the proportion of new infections on unit time.

We study the existence and uniqueness of a positive and periodic solution for equation (1).

A similiary integral equation which models the same problem

$$x(t) = \int_{t-\tau}^t f(s, x(s)) ds \quad (2)$$

has been considered in [4], [5], [9], [8], [13] and [10] where sufficient conditions for the existence of nontrivial periodic nonnegative and continous solutions for this equation are given in the case of a periodic contact rate: $f(t + \omega, x) = f(t, x)$, $\forall t \in \mathbb{R}$. The tools were: Banach fixed point principle in [10], topological fixed point theorems in [4], [5], [8], [13], fixed point index theory in [5] and monotone technique in [5], [8], [9]. Also, a system of integral equations in the form (2) has been studied in [2] and [11] using: the monotone technique in [2] and the Perov's fixed point theorem for differentiable dependence by the parameter of the solution in [11]. In [1], sufficient conditions for the existence and uniqueness of a positive, continuous solution of the following initial value problem

$$x(t) = \begin{cases} \int_{t-\tau}^t f(s, x(s), x'(s)) ds, & t \in [0, T] \\ \varphi(t), & t \in [-\tau, 0] \end{cases}$$

are obtained.

In the following, if X is a nonempty set then by a generalized metric d on X we understand a function $d : X \times X \rightarrow \mathbb{R}^n$ which fulfils the following:

$$\begin{aligned} 0_{\mathbb{R}^n} &\leq d(x, y), \forall x, y \in X \text{ and } d(x, y) = 0_{\mathbb{R}^n} \Leftrightarrow x = y \\ d(x, y) &= d(y, x), \forall x, y \in X \\ d(x, y) &\leq d(x, z) + d(z, y), \forall x, y, z \in X, \end{aligned}$$

where for $x = (x_1, x_2, \dots, x_n)$ and $y = (y_1, y_2, \dots, y_n)$ from \mathbb{R}^n we have $x \leq y \Leftrightarrow x_i \leq y_i$, for any $i = \overline{1, n}$. The pair (X, d) will be called generalized metric space.

2 Existence and uniqueness

We suppose that $f \in C(\mathbb{R} \times \mathbb{R}_+ \times \mathbb{R})$ and exists $\varpi > 0$ such that

$$f(t + \varpi, x, y) = f(t, x, y), \quad \forall (t, x, y) \in \mathbb{R} \times \mathbb{R}_+ \times \mathbb{R}.$$

We consider the following functional spaces

$$X(\varpi) = \{y \in C(\mathbb{R}) : y(t + \varpi) = y(t), \quad \forall t \in \mathbb{R}\}$$

$$X_1(\varpi) = \{x \in C^1(\mathbb{R}) : x(t + \varpi) = x(t), \quad \forall t \in \mathbb{R}\}$$

$$X_+(\varpi) = \{x \in X_1(\varpi) : x(t) \geq 0, \quad \forall t \in \mathbb{R}\}.$$

and denote by X the product space $X = X_+(\varpi) \times X(\varpi)$ which is generalized metric space with

$$d_C : X \times X \rightarrow \mathbb{R}^2, d_C((x_1, y_1), (x_2, y_2)) = (\|x_1 - x_2\|, \|y_1 - y_2\|),$$

where

$$\|u\| = \max\{|u(t)| : t \in [0, \varpi]\}$$

for any $u \in X(\varpi)$.

To obtain the existence and uniqueness result for the integro-differential equation (1) we use the following Perov's fixed point theorem [7] (see also [3], [6])

Theorem 1 (Perov, see [7]) *Let (X, d) a complete generalized metric space with $d(x, y) \in \mathbb{R}^n$. If $T : X \rightarrow X$ is a map for which exists a matrix $A \in \mathcal{M}_n(\mathbb{R})$ such that*

$$d(T(x), T(y)) \leq Ad(x, y), \forall x, y \in X$$

and the eigenvalues of A lies in the open unit disc from \mathbb{R}^2 , then T has a unique fixed point x^ and the sequence of successive approximations $x_m = T^m(x_0)$ converges to x^* for any $x_0 \in X$. Moreover, the following estimation holds*

$$d(x_m, x^*) \leq A^m (I_2 - A)^{-1} d(x_0, x_1), \forall m \in \mathbb{N}^*.$$

If we derive (1) with respect t and denoting $y(t) = x'(t)$ we obtain

$$y(t) = f(t, x(t), y(t)) - f(t - \tau, x(t - \tau), y(t - \tau)), \forall t \in \mathbb{R}.$$

which lead to

$$\begin{cases} x(t) = \int_{t-\tau}^t f(s, x(s), y(s)) ds \\ y(t) = f(t, x(t), y(t)) - f(t - \tau, x(t - \tau), y(t - \tau)) \end{cases} \quad (3)$$

Let $T : X \rightarrow C(\mathbb{R}) \times C(\mathbb{R})$ the map given by

$$T(x, y) = (T_1(x, y), T_2(x, y))$$

$$\begin{pmatrix} T_1(x, y)(t) \\ T_2(x, y)(t) \end{pmatrix} = \begin{pmatrix} \int_{t-\tau}^t f(s, x(s), y(s)) ds \\ f(t, x(t), y(t)) - f(t - \tau, x(t - \tau), y(t - \tau)) \end{pmatrix} \quad (4)$$

We impose the following conditions:

(i) $f \in C(\mathbb{R} \times \mathbb{R}_+ \times \mathbb{R})$ and exists $m, M \geq 0$ such that

$$m \leq f(t, x, y) \leq M, \forall (t, x, y) \in \mathbb{R} \times \mathbb{R}_+ \times \mathbb{R}.$$

(ii) f has the property

$$f(t + \varpi, x, y) = f(t, x, y), \forall (t, x, y) \in \mathbb{R} \times \mathbb{R}_+ \times \mathbb{R}.$$

(iii) exists $\alpha, \beta > 0$ such that

$$|f(t, u, v) - f(t, u', v')| \leq \alpha |u - u'| + \beta |v - v'|$$

$\forall t \in \mathbb{R}, \forall u, u' \in \mathbb{R}_+, \forall v, v' \in \mathbb{R}$.

From condition (i) we see that $T_1(X) \subseteq C^1(\mathbb{R})$ and

$$T_1(x, y)(t) = \int_{t-\tau}^t f(s, x(s), y(s)) ds \geq \int_{t-\tau}^t m ds = m\tau$$

$\forall t \in \mathbb{R}$. It is obvious that $T_1(x, y)(t) \leq M\tau \forall t \in \mathbb{R}, \forall (x, y) \in X$.

Theorem 2 *If the conditions (i)-(iii) are satisfied and $\alpha\tau + 2\beta < 1$ then the integro-differential equation (1) have in $X_+(\varpi)$ an unique solution.*

Proof. From condition (ii) follows that $T_1(X) \subset X_+(\varpi)$. Indeed,

$$\begin{aligned} T_1(x, y)(t + \varpi) &= \int_{t+\varpi-\tau}^{t+\varpi} f(s, x(s), y(s)) ds = \\ &= \int_{t-\tau}^t f(u - \varpi, x(u - \varpi), y(u - \varpi)) du = \\ &= \int_{t-\tau}^t f(u - \varpi + \varpi, x(u - \varpi + \varpi), y(u - \varpi + \varpi)) du = \\ &= T_1(x, y)(t), \quad \forall t \in \mathbb{R}, \forall (x, y) \in X. \end{aligned}$$

In addition

$$\begin{aligned} T_2(x, y)(t + \varpi) &= f(t + \varpi, x(t + \varpi), y(t + \varpi)) - \\ &\quad - f(t + \varpi - \tau, x(t + \varpi - \tau), y(t + \varpi - \tau)) = \\ &= f(t + \varpi, x(t), y(t)) - f(t + \varpi - \tau, x(t - \tau), y(t - \tau)) \\ &= f(t, x(t), y(t)) - f(t - \tau, x(t - \tau), y(t - \tau)) = T_2(x, y)(t) \end{aligned}$$

$\forall t \in \mathbb{R}, \forall (x, y) \in X$. Consequently, $T(X) \subset X$. Let $(x_1, y_1), (x_2, y_2) \in X$.

$$\begin{aligned} &|T_1(x_1, y_1)(t) - T_1(x_2, y_2)(t)| = \\ &= \left| \int_{t-\tau}^t f(s, x_1(s), y_1(s)) ds - \int_{t-\tau}^t f(s, x_2(s), y_2(s)) ds \right| \leq \\ &\leq \int_{t-\tau}^t |f(s, x_1(s), y_1(s)) - f(s, x_2(s), y_2(s))| ds \leq \end{aligned}$$

$$\begin{aligned} &\leq \int_{t-\tau}^t [\alpha |x_1(s) - x_2(s)| + \beta |y_1(s) - y_2(s)|] ds \leq \\ &\leq \alpha\tau \|x_1 - x_2\| + \beta\tau \|y_1 - y_2\|, \forall t \in [0, \varpi]. \end{aligned}$$

and

$$\begin{aligned} &|T_2(x_1, y_1)(t) - T_2(x_2, y_2)(t)| = |f(t, x_1(t), y_1(t)) - \\ &- f(t - \tau, x_1(t - \tau), y_1(t - \tau)) - f(t, x_2(t), y_2(t)) + \\ &+ f(t - \tau, x_2(t - \tau), y_2(t - \tau))| \leq |f(t, x_1(t), y_1(t)) - \\ &- f(t, x_2(t), y_2(t))| + |f(t - \tau, x_1(t - \tau), y_1(t - \tau)) - \\ &- f(t - \tau, x_2(t - \tau), y_2(t - \tau))| \leq \alpha |x_1(t) - x_2(t)| + \\ &+ \beta |y_1(t) - y_2(t)| + \alpha |x_1(t - \tau) - x_2(t - \tau)| + \\ &+ \beta |y_1(t - \tau) - y_2(t - \tau)| \leq 2\alpha \|x_1 - x_2\| + \\ &+ 2\beta \|y_1 - y_2\|, \forall t \in [0, \varpi], \forall (x_1, y_1), (x_2, y_2) \in X \end{aligned}$$

Then

$$\begin{aligned} &\left(\begin{array}{c} \|T_1(x_1, y_1) - T_1(x_2, y_2)\| \\ \|T_2(x_1, y_1) - T_2(x_2, y_2)\| \end{array} \right) \leq \\ &\leq \left(\begin{array}{c} \alpha\tau \|x_1 - x_2\| + \beta\tau \|y_1 - y_2\| \\ 2\alpha \|x_1 - x_2\| + 2\beta \|y_1 - y_2\| \end{array} \right) = \\ &= \left(\begin{array}{cc} \alpha\tau & \beta\tau \\ 2\alpha & 2\beta \end{array} \right) \cdot \left(\begin{array}{c} \|x_1 - x_2\| \\ \|y_1 - y_2\| \end{array} \right) \end{aligned}$$

that is

$$d_C(T(x_1, y_1), T(x_2, y_2)) \leq A \cdot d_C((x_1, y_1), (x_2, y_2))$$

The matrix

$$A = \left(\begin{array}{cc} \alpha\tau & \beta\tau \\ 2\alpha & 2\beta \end{array} \right) \quad (5)$$

has the eigenvalues $\lambda_1 = 0$ and $\lambda_2 = 2\beta + \alpha\tau$. Since $\alpha\tau + 2\beta < 1$, by the Perov's fixed point theorem we infer that T has in X an unique fixed point, denoted by $x_* = (x^*, y^*)$. It is easy to see that $(x^*)'(t) = y^*(t)$, $\forall t \in \mathbb{R}$. Indeed,

$$y^*(t) = f(t, x^*(t), y^*(t)) - f(t - \tau, x^*(t - \tau), y^*(t - \tau))$$

$$x^*(t) = \int_{t-\tau}^t f(s, x^*(s), y^*(s)) ds$$

and after derivation,

$$(x^*)'(t) = f(t, x^*(t), y^*(t)) - f(t - \tau, x^*(t - \tau), y^*(t - \tau))$$

Then, $x^* \in X_+(\varpi)$ is the solution of the equation (1). ■

From the above result, the solution x^* of (1) and his derivative are ϖ -periodic.

Theorem 3 In the conditions of Theorem 2 the solution x_* of (3), which is obtained by the successive approximations method starting from any $x^0 = (x_0, y_0) \in X$, verify the following estimation

$$d_C(x^m, x_*) \leq \frac{\lambda_2^{m-1}}{1 - \lambda_2} \begin{pmatrix} \alpha\tau & \beta\tau \\ 2\alpha & 2\beta \end{pmatrix} d_C(x^1, x^0).$$

where $x^m = T(x^{m-1})$, $x^m = (x_m, y_m)$, $\forall m \in \mathbb{N}^*$.

Proof. From Theorem 1, in conditions of Theorem 2 we have that

$$d_B(x^m, x^*) \leq A^m (I - A)^{-1} d_B(x^1, x^0), \forall m \in \mathbb{N}^*.$$

For the matrix A given in (5) we have $A^m = \lambda_2^{m-1} A$, $\forall m \in \mathbb{N}^*$ and $(I - A)^{-1} = \frac{1}{1 - \lambda_2} \begin{pmatrix} 1 - 2\beta & \beta\tau \\ 2\alpha & 1 - \alpha\tau \end{pmatrix}$. ■

The solution of (1) and his derivative can be obtained by the successive approximations method starting from any element of X .

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