



VICTORIA UNIVERSITY
MELBOURNE AUSTRALIA

On Weighted Simpson Type Inequalities and Applications

This is the Published version of the following publication

Tseng, Kuei-Lin, Yang, Gou-Sheng and Dragomir, Sever S (2004) On Weighted Simpson Type Inequalities and Applications. RGMIA research report collection, 7 (1).

The publisher's official version can be found at

Note that access to this version may require subscription.

Downloaded from VU Research Repository <https://vuir.vu.edu.au/17075/>

ON WEIGHTED SIMPSON TYPE INEQUALITIES AND APPLICATIONS

KUEI-LIN TSENG, GOU-SHENG YANG, AND SEVER S. DRAGOMIR

ABSTRACT. In this paper we establish some weighted Simpson type inequalities and give several applications for the r -moments and the expectation of a continuous random variable. An approximation for Euler's Beta mapping is given as well.

1. INTRODUCTION

The *Simpson's inequality*, states that if $f^{(4)}$ exists and is bounded on (a, b) , then

$$(1.1) \quad \left| \int_a^b f(t) dt - \frac{b-a}{3} \left[\frac{f(a) + f(b)}{2} + 2f\left(\frac{a+b}{2}\right) \right] \right| \leq \frac{(b-a)^5}{2880} \|f^{(4)}\|_\infty,$$

where

$$\|f^{(4)}\|_\infty := \sup_{t \in (a,b)} |f^{(4)}(t)| < \infty.$$

Now if we assume that $I_n : a = x_0 < x_1 < \dots < x_n = b$ is a partition of the interval $[a, b]$ and f is as above, then we can approximate the integral $\int_a^b f(t) dt$ by the *Simpson's quadrature formula* $A_S(f, I_n)$, having an error given by $R_S(f, I_n)$, where

$$(1.2) \quad A_S(f, I_n) := \sum_{i=0}^{n-1} \frac{l_i}{3} \left[\frac{f(x_i) + f(x_{i+1})}{2} + 2f\left(\frac{x_i + x_{i+1}}{2}\right) \right],$$

and the remainder $R_S(f, I_n) = \int_a^b f(t) dt - A_S(f, I_n)$ satisfies the estimation

$$(1.3) \quad |R_S(f, I_n)| \leq \frac{1}{2880} \|f^{(4)}\|_\infty \sum_{i=0}^{n-1} l_i^5,$$

with $l_i := x_{i+1} - x_i$ for $i = 0, 1, \dots, n-1$.

For some recent results which generalize, improve and extend this classic inequality (1.1), see the papers [2] – [7] and [9] – [12].

Recently, Dragomir [6], (see also the survey paper authored by Dragomir, Agarwal and Cerone [7]) has proved the following two Simpson type inequalities for functions of bounded variation:

Theorem 1. *Let $f : [a, b] \rightarrow \mathbb{R}$ be a mapping of bounded variation. Then*

$$(1.4) \quad \left| \int_a^b f(t) dt - \frac{b-a}{3} \left[\frac{f(a) + f(b)}{2} + 2f\left(\frac{a+b}{2}\right) \right] \right| \leq \frac{1}{3} (b-a) \bigvee_a^b(f),$$

Date: March 15, 2004.

2000 Mathematics Subject Classification. Primary 26D15, 26D10; Secondary 41A55.

Key words and phrases. Simpson Inequality, Weighted Inequalities, Quadrature Rules.

where $\bigvee_a^b(f)$ denotes the total variation of f on the interval $[a, b]$. The constant $\frac{1}{3}$ is the best possible.

Let I_n , l_i ($i = 0, 1, \dots, n-1$), $A_S(f, I_n)$ and $R_S(f, I_n)$ be as above. We have the following result concerning the approximation of the integral $\int_a^b f(t)dt$ in terms of $A_S(f, I_n)$.

Theorem 2. *Let f be defined as in Theorem 1. Then the remainder*

$$(1.5) \quad R_S(f, I_n) = \int_a^b f(x)dx - A_S(f, I_n)$$

satisfies the estimate

$$(1.6) \quad |R_S(f, I_n)| \leq \frac{1}{3} \nu(l) \bigvee_a^b(f),$$

where $\nu(l) := \max \{l_i \mid i = 0, 1, \dots, n-1\}$. The constant $\frac{1}{3}$ is best possible in (1.6).

In this paper, we establish some generalizations of Theorems 1 – 2, and give several applications for the r – moments and expectation of a continuous random variable. Approximations for Euler's Beta mapping are also provided.

2. SOME INTEGRAL INEQUALITIES

We may state and prove the following main result:

Theorem 3. *Let $g : [a, b] \rightarrow \mathbb{R}$ be positive and continuous and let $h(x) = \int_a^x g(t)dt$, $x \in [a, b]$. Let f be as in Theorem 3. Then*

$$(2.1) \quad \left| \int_a^b f(t)g(t)dt - \frac{1}{3} \left[\frac{f(a) + f(b)}{2} + 2f(h^{-1}(x)) \right] \int_a^b g(t)dt \right| \leq \left[\frac{1}{3}h(b) + \left| x - \frac{h(b)}{2} \right| \right] \cdot \bigvee_a^b(f),$$

for all $x \in \left[\frac{h(b)}{6}, \frac{5h(b)}{6} \right]$, where $\bigvee_a^b(f)$ denotes the total variation of f on the interval $[a, b]$. The constant $\frac{1}{3}$ is the best possible.

Proof. Fix $x \in \left[\frac{h(b)}{6}, \frac{5h(b)}{6} \right]$. Define

$$s(t) := \begin{cases} h(t) - \frac{h(b)}{6}, & t \in [a, h^{-1}(x)) \\ h(t) - \frac{5h(b)}{6}, & t \in [h^{-1}(x), b] \end{cases}.$$

By integration by parts, we have the following identity

$$(2.2) \quad \begin{aligned} & \int_a^b s(t) df(t) \\ &= \left[\left(h(t) - \frac{h(b)}{6} \right) f(t) \Big|_a^{h^{-1}(x)} - \int_a^{h^{-1}(x)} f(t)g(t)dt \right] \\ & \quad + \left[\left(h(t) - \frac{5h(b)}{6} \right) f(t) \Big|_{h^{-1}(x)}^b - \int_{h^{-1}(x)}^b f(t)g(t)dt \right] \end{aligned}$$

$$\begin{aligned}
&= \frac{1}{3} h(b) \left[\frac{f(a) + f(b)}{2} + 2f(h^{-1}(x)) \right] - \int_a^b f(t)g(t) dt \\
&= \frac{1}{3} \left[\frac{f(a) + f(b)}{2} + 2f(h^{-1}(x)) \right] \int_a^b g(t) dt - \int_a^b f(t)g(t) dt.
\end{aligned}$$

It is well known (see for instance [1, p. 159]) that, if $\mu, \nu : [a, b] \rightarrow \mathbb{R}$ are such that μ is continuous on $[a, b]$ and ν is of bounded variation on $[a, b]$, then $\int_a^b \mu(t) d\nu(t)$ exists and [1, p. 177]

$$(2.3) \quad \left| \int_a^b \mu(t) d\nu(t) \right| \leq \sup_{t \in [a, b]} |\mu(t)| \bigvee_a^b(\nu).$$

Now, using (2.2) and (2.3), we have

$$\begin{aligned}
(2.4) \quad \left| \int_a^b f(t)g(t) dt - \frac{1}{3} \left[\frac{f(a) + f(b)}{2} + 2f(h^{-1}(x)) \right] \int_a^b g(t) dt \right| \\
\leq \sup_{t \in [a, b]} |s(t)| \bigvee_a^b(f).
\end{aligned}$$

Since $h(t) - \frac{h(b)}{6}$ is increasing on $[a, h^{-1}(x))$, $h(t) - \frac{5h(b)}{6}$ is increasing on $[h^{-1}(x), b]$ and the fact that $\max\{c, d\} = \frac{c+d}{2} + \frac{1}{2}|c-d|$ for any real c and d , hence we have

$$\sup_{t \in [a, b]} |s(t)| = \max \left\{ \frac{h(b)}{6}, x - \frac{h(b)}{6}, \frac{5h(b)}{6} - x \right\}$$

and

$$\begin{aligned}
(2.5) \quad \sup_{t \in [a, b]} |s(t)| &= \max \left\{ \frac{h(b)}{6}, x - \frac{h(b)}{6}, \frac{5h(b)}{6} - x \right\} \\
&= \max \left\{ x - \frac{h(b)}{6}, \frac{5h(b)}{6} - x \right\} \\
&= \frac{1}{2} \left[\left(x - \frac{h(b)}{6} \right) + \left(\frac{5h(b)}{6} - x \right) \right] \\
&\quad + \frac{1}{2} \left| \left(x - \frac{h(b)}{6} \right) - \left(\frac{5h(b)}{6} - x \right) \right| \\
&= \frac{h(b)}{3} + \left| x - \frac{h(b)}{2} \right| \\
&= \frac{1}{3} \int_a^b g(t) dt + \left| x - \frac{1}{2} \int_a^b g(t) dt \right|.
\end{aligned}$$

Thus, by (2.4) and (2.5), we obtain the desired inequality (2.1).

Let us consider the particular functions:

$$\begin{aligned}
g(t) &\equiv 1, \quad t \in [a, b], \\
h(t) &= t - a, \quad t \in [a, b], \\
f(t) &= \begin{cases} 1 & \text{as } t \in [a, \frac{a+b}{2}) \cup (\frac{a+b}{2}, b] \\ -1 & \text{as } t = \frac{a+b}{2} \end{cases}
\end{aligned}$$

and $x = \frac{b-a}{2}$. Since for these choices we get equality in (2.1), it is easy to see that the constant $\frac{1}{3}$ is the best possible constant in (2.1). This completes the proof. ■

Remark 1. (1) If we choose $g(t) \equiv 1$, $h(t) = t - a$ on $[a, b]$ and $x = \frac{b-a}{2}$, then the inequality (2.1) reduces to (1.4).

(2) If we choose $x = \frac{h(b)}{2}$, then we get

$$(2.6) \quad \left| \int_a^b f(t)g(t) dt - \frac{1}{3} \left[\frac{f(a) + f(b)}{2} + 2f \left(h^{-1} \left(\frac{h(b)}{2} \right) \right) \right] \int_a^b g(t) dt \right| \leq \frac{1}{3} \int_a^b g(t) dt \cdot \bigvee_a^b(f).$$

Under the conditions of Theorem 3, we have the following corollaries.

Corollary 1. Let $f \in C^{(1)}[a, b]$. Then we have the inequality

$$(2.7) \quad \left| \int_a^b f(t)g(t) dt - \frac{1}{3} \left[\frac{f(a) + f(b)}{2} + 2f(h^{-1}(x)) \right] \int_a^b g(t) dt \right| \leq \left[\frac{1}{3} \int_a^b g(t) dt + \left| x - \frac{h(b)}{2} \right| \right] \|f'\|_1,$$

for all $x \in \left[\frac{h(b)}{6}, \frac{5h(b)}{6} \right]$, where $\|\cdot\|_1$ is the L_1 -norm, namely

$$\|f'\|_1 := \int_a^b |f'(t)| dt.$$

Corollary 2. Let $f : [a, b] \rightarrow \mathbb{R}$ be a Lipschitzian mapping with the constant $M > 0$. Then we have the inequality

$$(2.8) \quad \left| \int_a^b f(t)g(t) dt - \frac{1}{3} \left[\frac{f(a) + f(b)}{2} + 2f(h^{-1}(x)) \right] \int_a^b g(t) dt \right| \leq \left[\frac{1}{3} \int_a^b g(t) dt + \left| x - \frac{h(b)}{2} \right| \right] (b-a) M,$$

for all $x \in \left[\frac{h(b)}{6}, \frac{5h(b)}{6} \right]$.

Corollary 3. Let $f : [a, b] \rightarrow \mathbb{R}$ be a monotonic mapping. Then we have the inequality

$$(2.9) \quad \left| \int_a^b f(t)g(t) dt - \frac{1}{3} \left[\frac{f(a) + f(b)}{2} + 2f(h^{-1}(x)) \right] \int_a^b g(t) dt \right| \leq \left[\frac{1}{3} \int_a^b g(t) dt + \left| x - \frac{h(b)}{2} \right| \right] \cdot |f(b) - f(a)|$$

for all $x \in \left[\frac{h(b)}{6}, \frac{5h(b)}{6} \right]$.

3. APPLICATIONS FOR QUADRATURE FORMULAE

Throughout this section, let g, h be as in Theorem 3, $f : [a, b] \rightarrow \mathbb{R}$, and let $I_n : a = x_0 < x_1 < \dots < x_n = b$ be a partition of $[a, b]$, and $h_i(x) = \int_{x_i}^x g(t)dt$, $x \in [x_i, x_{i+1}]$, $\xi_i \in \left[\frac{h(x_{i+1})}{6}, \frac{5h(x_{i+1})}{6} \right]$ ($i = 0, 1, \dots, n-1$) are intermediate points. Put $L_i := h_i(x_{i+1}) = \int_{x_i}^{x_{i+1}} g(t)dt$ and define the sum

$$A_S(f, g, I_n, \xi) := \sum_{i=0}^{n-1} \frac{L_i}{3} \left[\frac{f(x_i) + f(x_{i+1})}{2} + 2f(h^{-1}(\xi_i)) \right]$$

and

$$R_S(f, g, I_n, \xi) = \int_a^b f(t)g(t)dx - A_S(f, g, I_n, \xi).$$

We have the following approximation of the integral $\int_a^b f(t)g(t)dt$.

Theorem 4. *Let f be defined as in Theorem 3 and let*

$$(3.1) \quad \int_a^b f(t)g(t)dt = A_S(f, g, I_n, \xi) + R_S(f, g, I_n, \xi).$$

Then, the remainder term $R_S(f, g, h, I_n, \xi)$ satisfies the estimate

$$(3.2) \quad \begin{aligned} |R_S(f, g, h, I_n, \xi)| &\leq \left[\frac{1}{3}\nu(L) + \max_{i=0,1,\dots,n-1} \left| \xi_i - \frac{h_i(x_{i+1})}{2} \right| \right] \bigvee_a^b(f) \\ &\leq \frac{2}{3}\nu(L) \bigvee_a^b(f), \end{aligned}$$

where $\nu(L) := \max \{L_i \mid i = 0, 1, \dots, n-1\}$. The constant $\frac{1}{3}$ in the first inequality of (3.2) is the best possible.

Proof. Apply Theorem 3 on the intervals $[x_i, x_{i+1}]$ ($i = 0, 1, \dots, n-1$) to get

$$\begin{aligned} \left| \int_{x_i}^{x_{i+1}} f(t)g(t)dt - \frac{L_i}{3} \left[\frac{f(x_i) + f(x_{i+1})}{2} + 2f(h_i^{-1}(\xi_i)) \right] \right| \\ \leq \left[\frac{1}{3}L_i + \left| \xi_i - \frac{h_i(x_{i+1})}{2} \right| \right] \bigvee_{x_i}^{x_{i+1}}(f), \end{aligned}$$

for all $i = 0, 1, \dots, n-1$. Using this and the generalized triangle inequality, we have

$$\begin{aligned}
& |R_S(f, g, I_n, \xi)| \\
& \leq \sum_{i=0}^{n-1} \left| \int_{x_i}^{x_{i+1}} f(t)g(t) dt - \frac{L_i}{3} \left[\frac{f(x_i) + f(x_{i+1})}{2} + 2f(h_i^{-1}(\xi_i)) \right] \right| \\
& \leq \sum_{i=0}^{n-1} \left[\frac{1}{3}L_i + \left| \xi_i - \frac{h_i(x_{i+1})}{2} \right| \right] \bigvee_{x_i}^{x_{i+1}}(f) \\
& \leq \max_{i=0,1,\dots,n-1} \left[\frac{1}{3}L_i + \left| \xi_i - \frac{h_i(x_{i+1})}{2} \right| \right] \sum_{i=0}^{n-1} \bigvee_{x_i}^{x_{i+1}}(f) \\
& \leq \left[\frac{1}{3}\nu(L) + \max_{i=0,1,\dots,n-1} \left| \xi_i - \frac{h_i(x_{i+1})}{2} \right| \right] \bigvee_a^b(f)
\end{aligned}$$

and the first inequality in (3.2) is proved.

For the second inequality in (3.2), we observe that

$$\left| \xi_i - \frac{h_i(x_{i+1})}{2} \right| \leq \frac{1}{3}L_i \quad (i = 0, 1, \dots, n-1);$$

and then

$$\max_{i=0,1,\dots,n-1} \left| \xi_i - \frac{h(x_i) + h(x_{i+1})}{2} \right| \leq \frac{1}{3}\nu(L).$$

Thus the theorem is proved. ■

Remark 2. If we choose $g(t) \equiv 1$, then $h(t) = t - a$ on $[a, b]$, $\xi_i = \frac{x_{i+1} - x_i}{2}$ ($i = 0, 1, \dots, n-1$), and the first inequality in (3.2) reduces to (1.6).

The following corollaries are useful in practice.

Corollary 4. Let $f : [a, b] \rightarrow \mathbb{R}$ be a Lipschitzian mapping with the constant $M > 0$, I_n be defined as above and choose $\xi_i = \frac{h_i(x_{i+1})}{2}$ ($i = 0, 1, \dots, n-1$). Then we have the formula

$$\begin{aligned}
(3.3) \quad \int_a^b f(t)g(t) dt &= A_S(f, g, I_n, \xi) + R_S(f, g, I_n, \xi) \\
&= \sum_{i=0}^{n-1} \frac{L_i}{3} \left[\frac{f(x_i) + f(x_{i+1})}{2} + 2f(h_i^{-1}(\xi_i)) \right] + R_S(f, g, I_n, \xi)
\end{aligned}$$

and the remainder satisfies the estimate

$$(3.4) \quad |R_S(f, g, I_n, \xi)| \leq \frac{\nu(L) \cdot M \cdot (b-a)}{3}.$$

Corollary 5. Let $f : [a, b] \rightarrow \mathbb{R}$ be a monotonic mapping and let ξ_i ($i = 0, 1, \dots, n-1$) be defined as in Corollary 4. Then we have the formula (3.3) and the remainder satisfies the estimate

$$(3.5) \quad |R_S(f, g, I_n, \xi)| \leq \frac{\nu(L)}{3} \cdot |f(b) - f(a)|.$$

The case of equidistant division is embodied in the following corollary and remark:

Corollary 6. Suppose that $G(x) = \int_a^x g(t)dt, x \in [a, b]$,

$$x_i = G^{-1} \left(\frac{i}{n} \int_a^b g(t)dt \right) \quad (i = 0, 1, \dots, n),$$

$$h_i(x) = \int_{x_i}^x g(t)dt, x \in [x_i, x_{i+1}], (i = 0, 1, \dots, n-1),$$

and

$$L_i := h_i(x_{i+1}) = G(x_{i+1}) - G(x_i) = \frac{1}{n} \int_a^b g(t)dt \quad (i = 0, 1, \dots, n-1).$$

Let f be defined as in Theorem 4 and choose $\xi_i = \frac{h_i(x_{i+1})}{2}$ ($i = 0, 1, \dots, n-1$). Then we have the formula

$$\begin{aligned} (3.6) \quad \int_a^b f(t)g(t)dt &= A_S(f, g, h, I_n, \xi) + R_S(f, g, h, I_n, \xi) \\ &= \frac{1}{3n} \sum_{i=0}^{n-1} \left[\frac{f(x_i) + f(x_{i+1})}{2} + 2f \left(h_i^{-1} \left(\frac{h_i(x_{i+1})}{2} \right) \right) \right] \int_a^b g(t)dt \\ &\quad + R_S(f, g, h, I_n, \xi) \end{aligned}$$

and the remainder satisfies the estimate

$$(3.7) \quad |R_S(f, g, h, I_n, \xi)| \leq \frac{1}{3n} \bigvee_a^b(f) \int_a^b g(t)dt.$$

Remark 3. If we want to approximate the integral $\int_a^b f(t)g(t)dt$ by $A_S(f, g, h, I_n, \xi)$ with an error less than $\varepsilon > 0$, then we need at least $n_\varepsilon \in \mathbb{N}$ points for the partition I_n , where

$$n_\varepsilon := \left\lceil \frac{1}{3\varepsilon} \int_a^b g(t)dt \cdot \bigvee_a^b(f) \right\rceil + 1$$

and $[r]$ denotes the Gaussian integer of $r \in \mathbb{R}$.

4. SOME INEQUALITIES FOR RANDOM VARIABLES

Throughout this section, let $0 < a < b$, $r \in \mathbb{R}$, and let X be a continuous random variable having the continuous probability density function $g : [a, b] \rightarrow [0, \infty)$ and assume the r -moment, defined by

$$E_r(X) := \int_a^b t^r g(t)dt,$$

is finite.

Theorem 5. The inequality

$$(4.1) \quad \left| E_r(X) - \frac{1}{6} \left[a^r + 4 \left(h^{-1} \left(\frac{1}{2} \right) \right)^r + b^r \right] \right| \leq \frac{1}{3} |b^r - a^r|$$

holds, where $h(t) = \int_a^t g(x)dx$ ($t \in [a, b]$).

Proof. If we put $f(t) = t^r$ and $x = \frac{h(b)}{2} = \frac{1}{2}$ in Corollary 3, then we obtain the inequality

$$(4.2) \quad \left| \int_a^b f(t)g(t) dt - \frac{1}{3} \left[\frac{f(a) + f(b)}{2} + 2f\left(h^{-1}\left(\frac{1}{2}\right)\right) \right] \int_a^b g(t) dt \right| \leq \frac{1}{3} |f(b) - f(a)| \int_a^b g(t) dt.$$

Since

$$\int_a^b f(t)g(t) dt = E_r(X), \quad \int_a^b g(t) dt = 1, \\ \frac{f(a) + f(b)}{2} = \frac{a^r + b^r}{2}, \text{ and } |f(b) - f(a)| = |b^r - a^r|,$$

(4.1) follows from (4.2). ■

If we choose $r = 1$ in Theorem 5, then we have the following remark:

Remark 4. If $E(X)$ is the expectation of random variable X , then

$$(4.3) \quad \left| E(X) - \frac{1}{6} \left[a + 4h^{-1}\left(\frac{1}{2}\right) + b \right] \right| \leq \frac{b-a}{3}.$$

5. INEQUALITY FOR THE BETA MAPPING

The following mapping is well-known in the literature as the *Beta mapping*:

$$\beta(p, q) := \int_0^1 t^{p-1} (1-t)^{q-1} dt, \quad p > 0, q > 0.$$

The following result may be stated:

Theorem 6. Let $p > 0, q > 1$. Then the inequality

$$(5.1) \quad \left| \beta(p, q) - \frac{1}{np} \sum_{i=0}^{n-1} \left\{ \frac{1}{6} \left(\left[1 - \left(\frac{i}{n} \right)^{\frac{1}{p}} \right]^{q-1} + \left[1 - \left(\frac{i+1}{n} \right)^{\frac{1}{p}} \right]^{q-1} \right) + \frac{2}{3} \left[1 - \left(\frac{2i+1}{2n} \right)^{\frac{1}{p}} \right]^{q-1} \right\} \right| \leq \frac{1}{3np}$$

holds for any positive integer n .

Proof. If we put $a = 0, b = 1, f(t) = (1-t)^{q-1}, g(t) = t^{p-1}$ and $G(t) = \frac{t^p}{p}$ ($t \in [0, 1]$) in Corollary 6, then,

$$\int_a^b g(t) dt = \frac{1}{p}, x_i = \left(\frac{i}{n} \right)^{\frac{1}{p}} \quad (i = 0, 1, \dots, n), \\ h_i(x) = \frac{nx^p - i}{np} \quad (x \in [x_i, x_{i+1}], i = 0, 1, \dots, n-1), \\ h_i^{-1} \left(\frac{h_i(x_{i+1})}{2} \right) = \left(\frac{2i+1}{2n} \right)^{\frac{1}{p}} \quad (i = 0, 1, \dots, n-1)$$

and $\bigvee_a^b(f) = 1$, so that the inequality (5.1) holds. ■

REFERENCES

- [1] T. M. Apostol, *Mathematical Analysis*, Second Edition, Addison-Wesley Publishing Company, 1975.
- [2] D. Cruz-Urible and C. J. Neugebauer, Sharp error bounds for the trapezoidal rule and Simpson's rule, *J. Inequal. Pure Appl. Math.* **3**(2002), no. 4, Article 49, 22 pp. [Online: http://jipam.vu.edu.au/v3n4/031_02.html].
- [3] V. Čuljak, J. Pečarić and L. E. Persson, A note on Simpson's type numerical integration, *Soochow J. Math.* **29**(2003), no. 2, 191-200.
- [4] S. S. Dragomir, On Simpson's quadrature formula and applications, *Mathematica* **43**(66) (2001), no. 2, 185-194 (2003).
- [5] S. S. Dragomir, On Simpson's quadrature formula for Lipschitzian mappings and applications, *Soochow J. Math.* **25**(1999), no. 2, 175-180.
- [6] S. S. Dragomir, On Simpson's quadrature formula for mappings of bounded variation and applications, *Tamkang J. of Math.* **30**(1999), no. 1, 53-58.
- [7] S. S. Dragomir, R. P. Agarwal and P. Cerone, On Simpson's inequality and applications, *J. Inequal. Appl.* **5**(2000), no. 6, 533-579.
- [8] L. Fejér, Ueber die Fourierreihen, II, *Math. Natur. Ungar. Akad. Wiss.* **24**(1906), 369-390. [In Hungarian].
- [9] J. Pečarić and S. Varošanec, A note on Simpson's inequality for Lipschitzian functions, *Soochow J. Math.* **27**(2001), no. 1, 53-57.
- [10] J. Pečarić and S. Varošanec, A note on Simpson's inequality for functions of bounded variation, *Tamkang J. of Math.* **31**(2000), no. 3, 239-242.
- [11] N. Ujević, New bounds for Simpson's inequality, *Tamkang J. of Math.* **33**(2002), no. 2, 129-138.
- [12] G. S. Yang and H. F. Chu, A note on Simpson's inequality for function of bounded variation, *Tamsui Oxford J. Math. Sci.* **16**(2000), no. 2, 229-240.

(Kuei-Lin Tseng) DEPARTMENT OF MATHEMATICS, ALETHEIA UNIVERSITY, TAMSUI, TAIWAN 25103

E-mail address, Kuei-Lin Tseng: kltseng@email.au.edu.tw

(Gou-Sheng Yang) DEPARTMENT OF MATHEMATICS, TAMKANG UNIVERSITY, TAMSUI, TAIWAN 25137

(Sever S. Dragomir) SCHOOL OF COMPUTER SCIENCE & MATHEMATICS, VICTORIA UNIVERSITY, MELBOURNE, VICTORIA, AUSTRALIA

E-mail address, Sever S. Dragomir: sever@matilda.vu.edu.au

URL: <http://rgmia.vu.edu.au/SSDragomirWeb.html>